

# CS711008Z Algorithm Design and Analysis

## Lecture 6. Hidden Markov model and Viterbi's decoding algorithm

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- The occasionally dishonest casino: an example of HMM
- Formal definition of HMM
- Finding the most probable state path: Viterbi algorithm

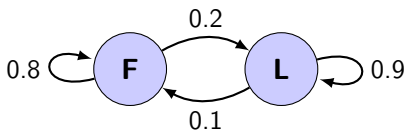
## The occasionally dishonest casino: an example of HMM

# The occasionally dishonest casino

- A casino have a **fair dice** and a **loaded dice**. The fair dice has identical probability  $\frac{1}{6}$  for all numbers one to six while the loaded dice has probability 0.3 of a five, 0.3 of a six, and 0.1 for the numbers one to four.
- For the first roll, the casino uses the fair dice with probability  $\frac{3}{5}$  and uses the loaded one with probability  $\frac{2}{5}$ . In the subsequent rolls, the casino switches from a fair to a loaded dice with probability 0.2 and switches back with probability 0.1. Thus the switch between dice forms a **Markov process**.

## Fair dice

1	: 1/6
2	: 1/6
3	: 1/6
4	: 1/6
5	: 1/6
6	: 1/6



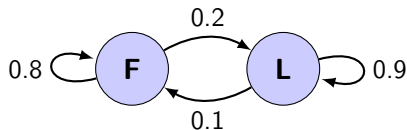
## Loaded dice

1	: 1/10
2	: 1/10
3	: 1/10
4	: 1/10
5	: 3/10
6	: 3/10

# The occasionally dishonest casino cont'd

## Fair dice

1	: 1/6
2	: 1/6
3	: 1/6
4	: 1/6
5	: 1/6
6	: 1/6



## Loaded dice

1	: 1/10
2	: 1/10
3	: 1/10
4	: 1/10
5	: 3/10
6	: 3/10

- Question: Suppose we observed a total of 10 rolls with the following outcomes:

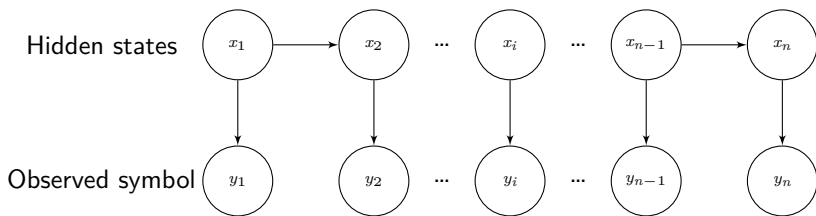
$$Y = (1, 3, 4, 5, 5, 6, 6, 3, 2, 6)$$

Could we find out the most probable state sequence, i.e. the most probable dice used for each roll?

# Trial 1: Calculating log-odd score based on Markov model

- For each observed symbol, we could calculate log-odd score for a window of  $w$  rolls around it, and expect the rolls using fair dice to stand out with positive values.
- However, this is unsatisfactory since:
  - This solution depends heavily on the selection of the window size  $w$ .
  - The rolls generated using fair dice might have sharp boundaries and variable length.
- A better idea is to build a model to describe the switch between these two dice.

# Trial 2: Calculating the most probable state path using HMM



- In each state of the Markov process, the outcome of a roll has different probability. Thus, the whole process forms a **hidden Markov model**. Here the **state sequence**, i.e. the dice used for each roll, is hidden.
- The essential difference between a Markov chain and a hidden Markov model is that for a HMM, there is not a one-to-one correspondence between observed symbols and states.

# Formal definition of HMM

- **Transition probability:** We now distinguish the sequence of states (denoted as  $X$ ) and the sequence of observed symbols (denoted as  $Y$ ). The state sequence follows a simple Markov chain, so the probability of a state  $x_i$  depends only on the previous one  $x_{i-1}$ , which is characterised using transition probability:

$$a_{kl} = P(x_i = l | x_{i-1} = k)$$

- **Begin state:** To model the beginning of the process we introduce a **begin state** (denoted as state 0). The transition probability  $a_{0k}$  represents the probability of starting in state  $k$ .
- **Emission probability:** A state can generate a symbol from a distribution over all possible symbols; thus, we define **emission probability:**

$$e_k(b) = P(y_i = b | x_i = k)$$



# Using HMM as a generative model

- A symbol sequence can be generated from HMM as follows:
  - Initially a state  $x_1$  is chosen according to the probability  $a_{0k}$ . In this state  $x_i$ , a symbol is emitted according to the emission probability  $e_{x_i}$ .
  - Then a new state  $x_2$  is generated according to the transition probability  $a_{x_1k}$  and so on. This way a symbol sequence  $Y = (y_1, y_2, \dots, y_n)$  is generated. Here we assume  $n$  is a fixed number and thus avoid defining an “end state” for simplicity.
- The joint probability of an observed symbol sequence  $Y$  and state sequence  $X$  is:

$$P(X, Y) = P(x_1 x_2 \dots x_n, y_1 y_2 \dots y_n) = \prod_{i=1}^n (a_{x_{i-1}x_i} e_{x_i}(y_i))$$

# An example

- For example, given an observed outcome of 10 rolls  $Y = (1, 3, 4, 5, 5, 6, 6, 3, 2, 6)$ , if  $X = (F, F, F, F, F, L, L, L, L, L)$ , we have:

$$P(X, Y) = \frac{3}{5} \times \left(\frac{1}{6}\right)^5 \times (0.8)^4 \times 0.2 \times \left(\frac{3}{10}\right)^3 \times \left(\frac{1}{10}\right)^2 \times 0.9^4$$

- There are a total of  $2^n$  possible state sequence. If we are to choose just one sequence, perhaps the one with the highest joint probability should be chosen,

$$X^* = \operatorname{argmax}_X P(X, Y)$$

# Viterbi's decoding algorithm [1967]

- In 1967, Andrew Viterbi proposed a dynamic programming algorithm for decoding over noisy communication links.
- The idea can be extended for decoding in general graphical models, including Bayesian networks, Markov random fields and CRF. The extension is usually termed as **max-sum algorithm**, which aims to finding the most probable latent variables in graphical models. In these models, the **forward-backward algorithm** was generalized to **message passing** or **belief propagation**.
- A faster implementation of Viterbi's algorithm is LAZYVITERBI (J. Feldman, et al, 2002). The algorithm was built upon  $A^*$  algorithm, and it does not expand any nodes until it really needs to do so.

# Viterbi's decoding algorithm: recursion

- First we rewrite  $\max_X P(X, Y)$  as:

$$\max_{x_n} \max_{x_{n-1}} \dots \max_{x_1} e_{x_n}(y_n) a_{x_{n-1}x_n} e_{x_{n-1}}(y_{n-1}) \dots a_{x_1x_2} e_{x_1}(y_1) a_{0x_1}$$

- Note that we cannot build a direct recursion between  $P(x_1x_2 \dots x_n, y_1y_2 \dots y_n)$  and  $P(x_2x_3 \dots x_n, y_2y_3 \dots y_n)$ .
- Let's consider a smaller subproblem: define  $v_i(k)$  as

$$\max_{x_{i-1}} \dots \max_{x_1} e_k(y_i) a_{x_{i-1}k} e_{x_{i-1}}(y_{i-1}) \dots a_{x_1x_2} e_{x_1}(y_1) a_{0x_1}$$

We can observe the following recursion:

$$v_i(k) = e_k(y_i) \max_l (a_{lk} v_{i-1}(l))$$

- We also have

$$\max_X P(X, Y) = \max_k v_n(k)$$

# Viterbi's decoding algorithm

VITERBIDECODING( $Y, a, e$ )

- 1: Initialize  $v_1(k) = a_{0k}e_k(y_1)$  for all state  $k$ ;
- 2: **for**  $i = 2$  to  $n$  **do**
- 3:     **for** each state  $k$  **do**
- 4:          $v_i(k) = e_k(y_i) \max_l(a_{lk}v_{i-1}(l))$ ;
- 5:          $ptr_i(k) = argmax_l(a_{lk}v_{i-1}(l))$ ;
- 6:     **end for**
- 7: **end for**
- 8:  $P(X^*, Y) = max_k(v_n(k))$ ;
- 9:  $x_n^* = argmax_k(v_n(k))$ ;
- 10: **for**  $i = n - 1$  to  $1$  **do**
- 11:      $x_i^* = ptr_{i-1}(x_{i+1}^*)$ ;
- 12: **end for**
- 13: **return**  $X$ ;

Time complexity:  $O(nK^2)$ , where  $K$  denotes the number of possible states

# An example

	$y_i$	$v_i(\text{F})$	$ptr_i(\text{F})$	$v_i(\text{L})$	$ptr_i(\text{L})$
$i = 1$	1	$1.000 * 10^{-1}$	-	$4.000 * 10^{-2}$	-
$i = 2$	3	$1.333 * 10^{-2}$	F	$3.600 * 10^{-3}$	L
$i = 3$	4	$1.778 * 10^{-3}$	F	$3.240 * 10^{-4}$	L
$i = 4$	5	$2.370 * 10^{-4}$	F	$1.067 * 10^{-4}$	F
$i = 5$	5	$3.161 * 10^{-4}$	F	$2.880 * 10^{-5}$	L
$i = 6$	6	$4.214 * 10^{-6}$	F	$7.776 * 10^{-6}$	L
$i = 7$	6	$5.619 * 10^{-7}$	F	$2.100 * 10^{-6}$	L
$i = 8$	3	$7.492 * 10^{-8}$	F	$1.890 * 10^{-7}$	L
$i = 9$	2	$9.989 * 10^{-9}$	F	$1.701 * 10^{-8}$	L
$i = 10$	6	$1.332 * 10^{-9}$	F	$4.592 * 10^{-9}$	L

